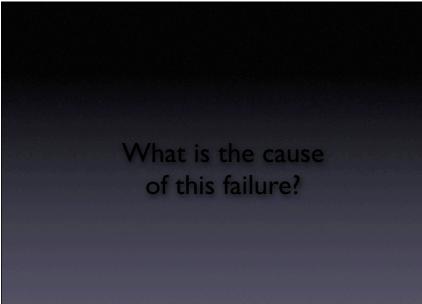


### bug.c

```
double bug(double z[], int n) {
    int i, j;
    i = 0;
    for (j = 0; j < n; j++) {
        i = i + j + 1;
        z[i] = z[i] * (z[0] + 1.0);
    }
    return z[n];
}</pre>
```



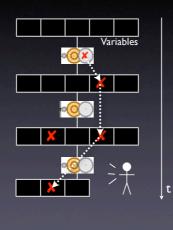
### What do we do now?



### From Defect to Failure

- 1. The programmer creates a *defect* an error in the code.
- When executed, the defect creates an *infection* – an error in the state.
- 3. The infection *propagates*.
- 4. The infection causes a failure.

This infection chain must be traced back – and broken.

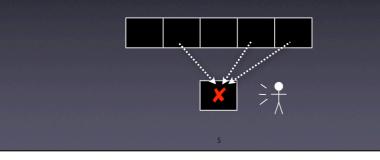


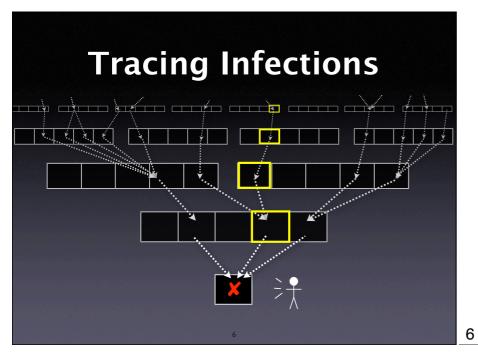
5



# **Tracing Infections**

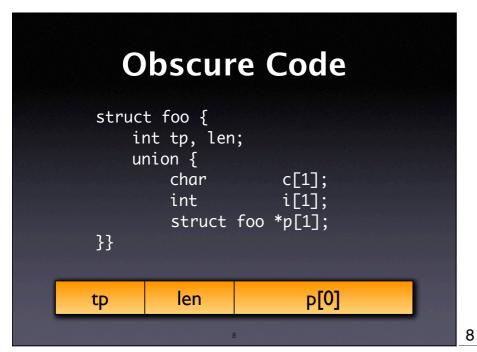
- For every infection, we must find the earlier infection that causes it.
- Program analysis tells us possible causes



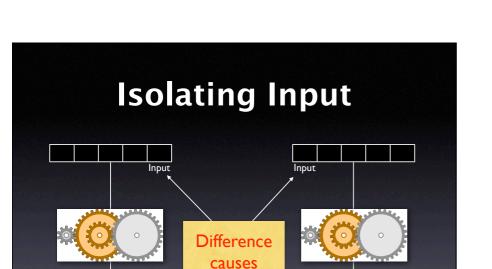


## **Real Code**

- Opaque e.g. third-party code
- Parallel threads and processes
- Distributed across multiple machines
- Dynamic e.g. reflection in Java
- Multilingual say, Python + C + SQL

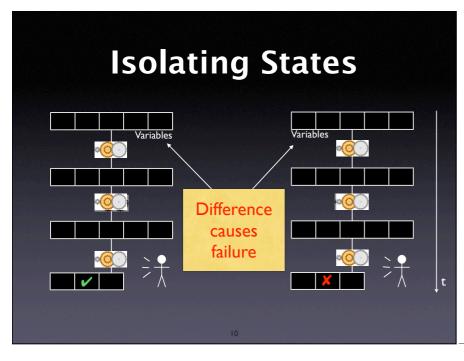



And even if we know everything, there still is code which is almost impossible to analyze. In C, for instance, only the programmer knows how memory is structured; there is no general way for static analysis to find this out



failure

In the last lecture, we have seen delta debugging on input.



Now let's take a deeper view. If a program is a succession of states, can't we treat each state as an input to the remainder of the run?

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# • What is a program state, anyway? • How can we compare states? • How can we narrow down differences?

### A Sample Program

\$ sample 9 8 7
Output: 7 8 9

\$ sample 11 14
Output: 0 11

Where is the defect which causes this failure?

# Let's look at a simpler example first.

### int main(int argc, char \*argv[]) { int \*a; // Input array a = (int \*)malloc((argc - 1) \* sizeof(int)); for (int i = 0; i < argc - 1; i++)</pre> a[i] = atoi(argv[i + 1]); // Sort array shell\_sort(a, argc); // Output array printf("Output: "); for (int i = 0; i < argc - 1; i++) printf("%d ", a[i]); printf("\n"); \_\_\_\_\_</pre> free(a); return 0; 3 13

# A sample state • We can access the entire state via the debugger: I. List all base variables 2. Expand all references... 3. ... until a fixpoint is found

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### **Sample States**

Variable	Va	lue	Variable	Va	lue
	in r,	in $r_{\mathbf{x}}$		in r,	in <i>ì</i>
argc	4	5	i	3	2
argv[0]	"./sample"	"./sample"	a[0]	9	11
argv[1]	"9"	"11"	a[1]	8	14
argv[2]	"8"	"14"	a[2]	7	0
argv[3]	"7"	0x0 (NIL)	a[3]	1961	196
<i>i'</i>	1073834752	1073834752	a'[0]	9	11
j	1074077312	1074077312	a'[1]	8	14
h	1961	1961	a'[2]	7	0
size	4	3	a'[3]	1961	196

<u>at shell\_sort()</u>

# Narrowing State Diffs

### **=** $\delta$ is applied, $\Box$ = $\delta$ is *not* applied

#	ŧ a	e'[0]	a[0]	a'[1]	a[1]	a'[2]	a[2]	argc	argv[1]	argv[2]	argv[3	] i size	Οι	utput	Test
1													7	89	~
2	2												0	11	×
3	;												0	11 14	×
4	ŀ												7	11 14	?
5	,												0	9 14	×
6	5												7	9 14	?
7	7												0	89	×
8	3												0	89	X
R	les	ult													
									16	,					

16	
10	

n de ser la s La ser la ser
n en generaliset en generaliset a papar en en generaliset en de set en generaliset en en en generaliset en en Rechter en antender state en das des trickens de state des ender handes antender en de service en als de servic
17

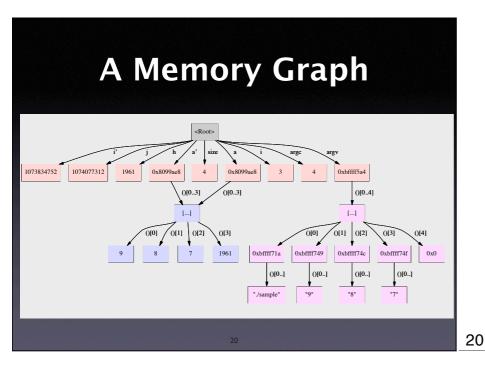
### Since this worked so well, we built a debugging server.



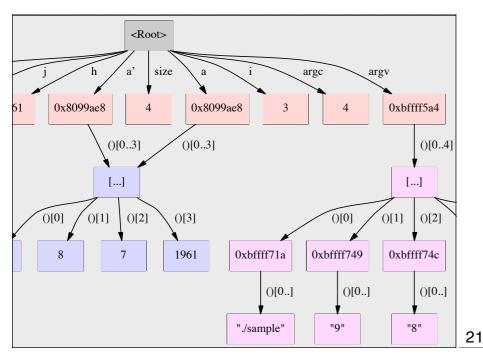
## **Complex State**

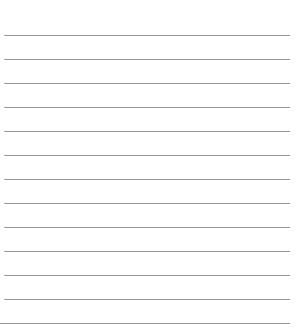
- Accessing the state as a *table* is not enough:
  - References are not handled
  - Aliases are not handled
- We need a *richer* representation

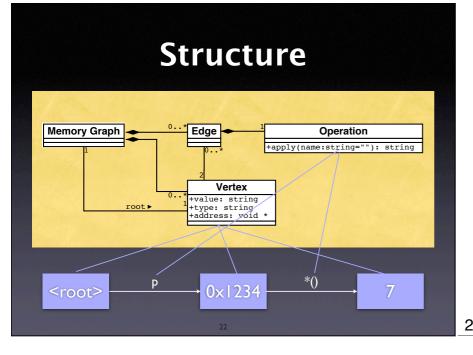


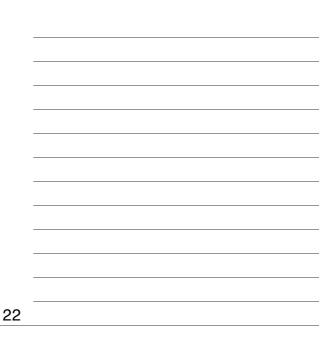












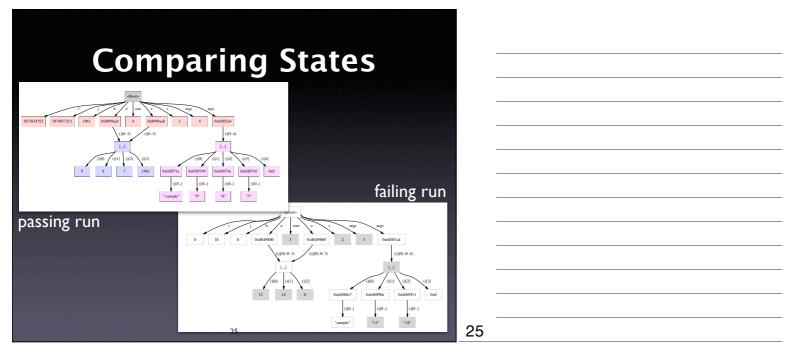
### Construction

- Start with <root> node and base variables
  - Base variables are on the stack and at fixed locations
- Expand all references, checking for aliases...
- ...until all accessible variables are unfolded

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### **Unfolding Memory**

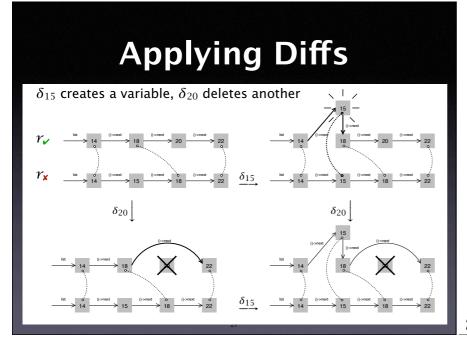
- Any variable: make new node
- Structures: unfold all members
- Arrays: unfold all elements
- Pointers: unfold object being pointed to
  - Does p point to something? And how many?

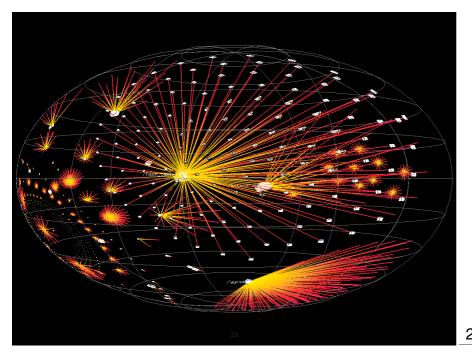


### **Comparing States**

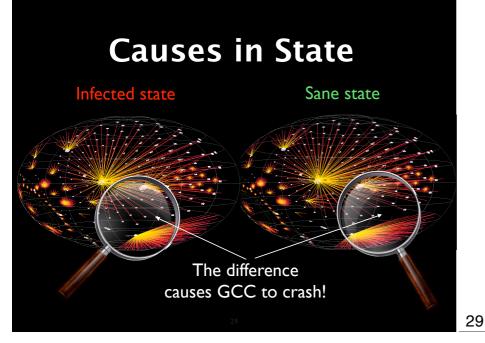
- Basic idea: compute common subgraph
- Any node that is not part of the common subgraph becomes a *difference*
- Applying a difference means to create or delete nodes and adjust references
- All this is done within GDB



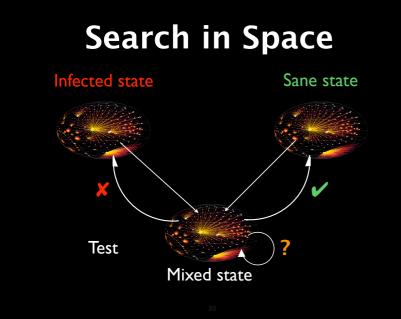




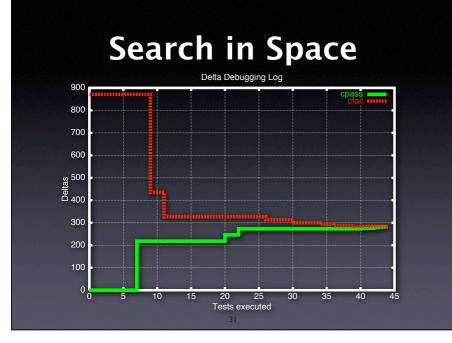
Stat	e of the GNU compiler
(GCC	.)
4299	01 vertices
4429	00 edges - and 1 is
wron	ng :-)
An a	ictual GCC execution has
mill	ions of these states.

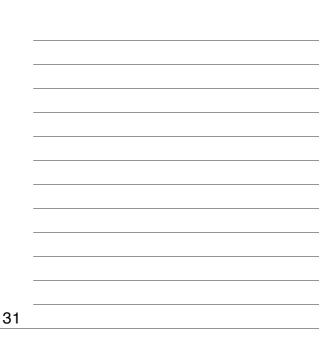


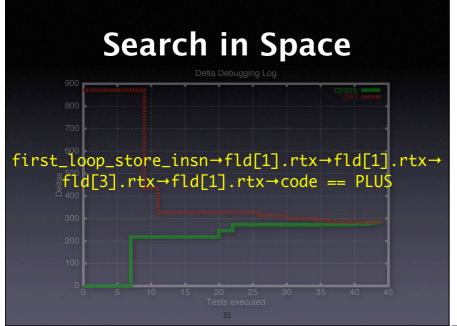


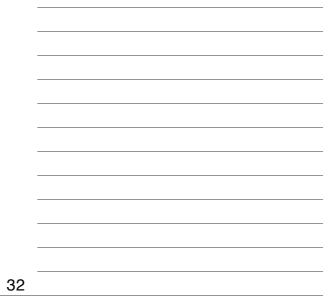


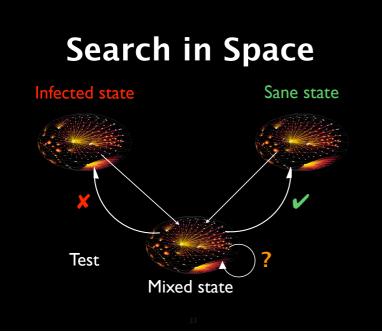






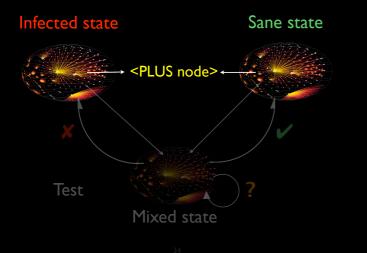








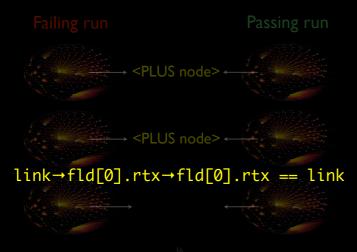
### Search in Space




# <figure><figure><figure><figure><complex-block>

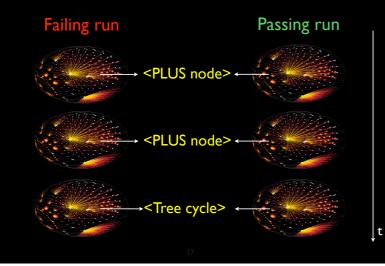
05		
35		

# Search in Time

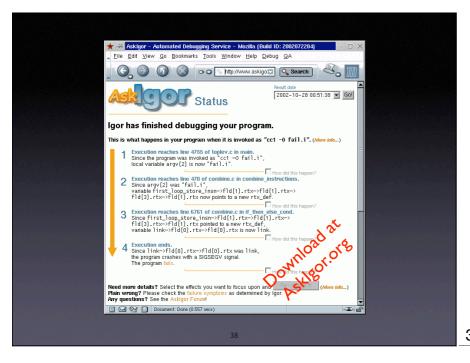


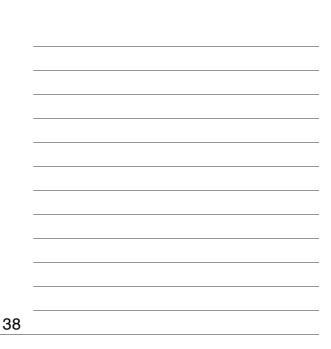


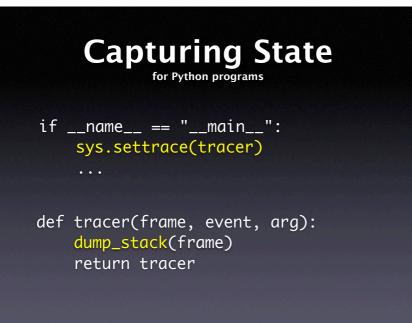
### Search in Time



07
37







### **Capturing State**

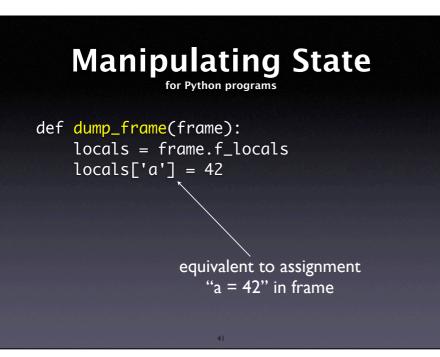
for Python programs

def dump\_stack(frame):

while frame is not None: dump\_frame(frame) frame = frame.f\_back

def dump\_frame(frame):
 locals = frame.f\_locals
 globals = frame.f\_globals
 print locals, globals

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### Caveats

Python frame objects are translated back to internal frames only after tracer() has returned:

- Frames can be inspected at any time, but changed only in tracer()
- Output of variables during tracer() may inhibit their translation at return

### **Open Issues**

- How do we capture an accurate state?
- How do we ensure the cause is valid?
- Where does a state end?
- What is the cost?
- When do we compare states? (next lecture)

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### Concepts

- Delta Debugging on program states isolates a cause-effect chain through the run
- ★ Use memory graphs to extract and compare program states
- ★ Demanding, yet effective technique



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