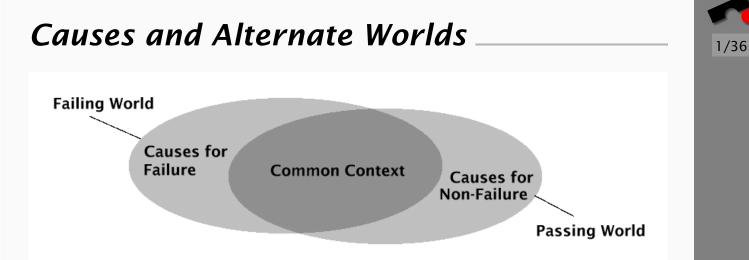


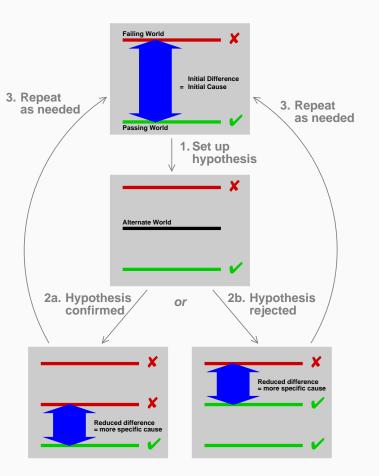
Isolating Failure Causes

Andreas Zeller

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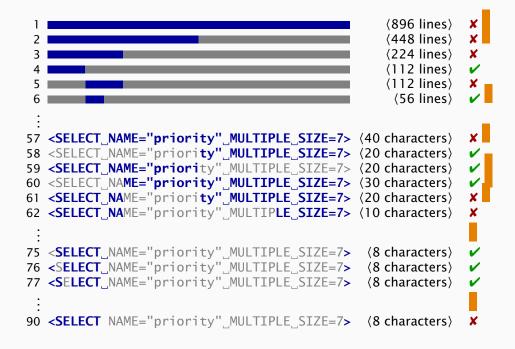
The Narrowing Process







Idea: Apply Divide and Conquer to simplify HTML pages

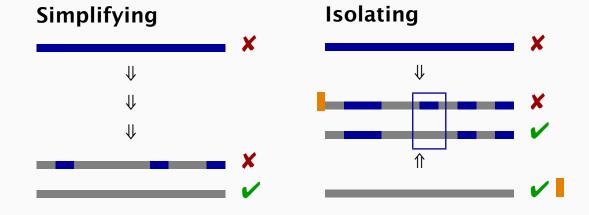


Simplified bug report: Printing <SELECT> crashes.

Simplifying vs. Isolating

Problem: To simplify the entire input can be expensive

Alternative approach: We do not simplify the entire input, but the *difference* with respect to a *working input*.



Larger context - but fewer tests and smaller causes





Isolating a HTML difference

Mozilla input

- 1 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> X
- 4 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> X
- 7 SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 6 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 5 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 3 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 2 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> /

Isolated difference: the "<" in "<SELECT>".

Isolating requires 7 tests, simplifying 26.

5/36

Test

Simplification vs. Isolation

Simplification

- make *each part* of the simplified test case relevant
- removing any part makes the failure go away

Isolation

- find *one* relevant part of the test case
- removing *this particular part* makes the failure go away

Both simplification and isolation can be handled by delta debugging.





$$ddmin(c_{\mathbf{x}}) = ddmin'(c_{\mathbf{x}}, 2) \text{ where}$$

$$ddmin'(c'_{\mathbf{x}}, n) = \begin{cases} ddmin'(\nabla_i, \max(n-1,2)) & \text{if } \exists i \in \{1, \dots, n\} \\ \cdot test(\nabla_i) = \mathbf{x} \\ ddmin'(c'_{\mathbf{x}}, \min(2n, |c_{\mathbf{x}}|)) & \text{if } 2n < |c_{\mathbf{x}}| \\ c'_{\mathbf{x}} & \text{otherwise} \end{cases}$$

$$\text{with } c'_{\mathbf{x}} = \Delta_1 \cup \Delta_2 \cup \cdots \cup \Delta_n, \nabla_i = c'_{\mathbf{x}} \setminus \Delta_i, \text{ and}$$

$$\forall \Delta_i, \Delta_j \cdot \Delta_i \cap \Delta_j = \emptyset \land |\Delta_i| \approx |\Delta_j|.$$

The *ddmin* algorithm must be *extended* to compute *differences*.





A new Algorithm

Let us try to *formalize* our issues.

Again, we have $c_{\mathbf{v}}$, $c_{\mathbf{x}}$, C, etc. as defined for *ddmin*.

Our goal is to find two sets $c'_{\mathbf{v}}$ and $c'_{\mathbf{x}}$ such that

- $\emptyset = c_{\checkmark} \subseteq c'_{\checkmark} \subset c'_{\varkappa} \subseteq c_{\varkappa}$ holds and
- the difference $\Delta = c'_{\mathbf{x}} c'_{\mathbf{v}}$ is *1-minimal*.

 Δ is *1-minimal* if

 $\forall \delta_i \in \Delta \cdot test(c'_{\checkmark} \cup \{\delta_i\}) \neq \checkmark \wedge test(c'_{\bigstar} - \{\delta_i\}) \neq \bigstar$

holds.







Extending ddmin

We must extend *ddmin* such that it works on *two sets at a time:*

- The failing test case $c'_{\mathbf{x}}$ which is to be *minimized* (initially, $c'_{\mathbf{x}} = c_{\mathbf{x}}$ holds), and
- The passing test case c'_{\checkmark} which is to be *maximized* (initially, $c'_{\checkmark} = c_{\checkmark} = \emptyset$ holds).



A Binary Search Approach

Basic idea:

- We split the difference $\Delta = c'_{\mathbf{x}} c'_{\mathbf{v}}$ into two subsets Δ_1 and Δ_2 .
 - $\Delta = \Delta_1 \cup \Delta_2$, $\Delta_1 \cap \Delta_2 = \emptyset$, and $|\Delta_1| \approx |\Delta_2|$ holds.
- We test two configurations:

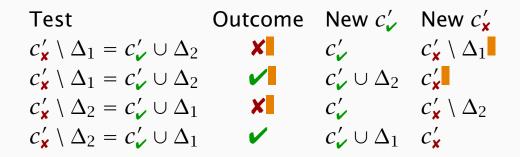
$$- c'_{\mathbf{x}} \setminus \Delta_1 = c'_{\mathbf{v}} \cup \Delta_2 \text{ and}$$
$$- c'_{\mathbf{x}} \setminus \Delta_2 = c'_{\mathbf{v}} \cup \Delta_1$$





Possible Outcomes

Starting with $c'_{\checkmark} = c_{\checkmark}$, $c'_{\varkappa} = c_{\varkappa}$; $\Delta = c'_{\varkappa} - c'_{\checkmark} = \Delta_1 \cup \Delta_2$.



Classical binary search with $O(\log_2 |\Delta|)$ tests.



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The ddbin Algorithm

Given: test, $c_{\mathbf{x}}, c_{\mathbf{x}} \cdot c_{\mathbf{x}} \subseteq c_{\mathbf{x}} \wedge test(c_{\mathbf{x}}) = \mathbf{v} \wedge test(c_{\mathbf{x}}) = \mathbf{X}$. Goal: $c'_{\checkmark}, c'_{\bigstar} = ddbin(c_{\checkmark}, c_{\bigstar})$ such that $c_{\checkmark} \subseteq c'_{\checkmark} \subseteq c'_{\bigstar} \subseteq c'_{\bigstar} \subseteq c'_{\bigstar}$ $test(c'_{\star}) = \checkmark, test(c'_{\star}) = \bigstar$ and each element of $\Delta = c'_{\mathbf{x}} \setminus c'_{\mathbf{y}}$ is relevant for the failure. Let $\Delta = c'_{\star} \setminus c'_{\star} = \Delta_1 \cup \Delta_2$ in $ddbin(c_{\star}, c_{\star}) = ddbin'(c_{\star}, c_{\star})$ where $ddbin'(c'_{\mathbf{v}},c'_{\mathbf{x}}) = \begin{cases} (c'_{\mathbf{v}},c'_{\mathbf{x}}) & \text{if } |\Delta| = 1 \\ ddbin'(c'_{\mathbf{v}},c'_{\mathbf{v}}\cup\Delta_2) & \text{if } test(c'_{\mathbf{v}}\cup\Delta_2) = \mathbf{x} \\ ddbin'(c'_{\mathbf{v}},\Delta_2,c'_{\mathbf{x}}) & \text{if } test(c'_{\mathbf{v}}\setminus\Delta_2) = \mathbf{x} \\ ddbin'(c'_{\mathbf{v}},c'_{\mathbf{v}}\cup\Delta_1) & \text{if } test(c'_{\mathbf{v}}\setminus\Delta_2) = \mathbf{x} \\ ddbin'(c'_{\mathbf{v}},c'_{\mathbf{v}}\cup\Delta_1) & \text{if } test(c'_{\mathbf{v}}\cup\Delta_1) = \mathbf{x} \\ ddbin'(c'_{\mathbf{x}}\setminus\Delta_1,c'_{\mathbf{x}}) & \text{if } test(c'_{\mathbf{x}}\setminus\Delta_1) = \mathbf{x} \end{cases}$

(Note that $c'_{\mathbf{x}} \setminus \Delta_1 = c'_{\mathbf{v}} \cup \Delta_2$ and $c'_{\mathbf{x}} \setminus \Delta_2 = c'_{\mathbf{v}} \cup \Delta_1$ hold.)

Classical binary search!



Mozilla input

- Test
- SELECT_NAME="priority"_MULTIPLE_SIZE=7> X
- 4 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> X
- 7 SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 6 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 5 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> / 3 <SELECT_NAME="priority"_MULTIPLE_SIZE=7> /
- 2 <SELECT_NAME="priority"_MULTIPLE_SIZE=7>



Problem: ddbin does not handle unresolved test outcomes!

14/36

Step GCC input test #define SIZE 20 ... double **mult**(...) $\{\ldots\}$ X 2 #define SIZE 20 3 double $mult(...) \{ \ldots \}$ X 1 double **mult**(...) { int i, j; i = 0; } 4 double **mult**(...) { for(...) { ... } ... } ? 5

Unresolved Test Outcomes (2)

The *more we change* some input which has a *resolved* test outcome (✔ or ¥),

- the *faster* the progress in narrowing the difference, but
- the *higher* are the chances of unresolved outcomes (?).

If we apply *smaller changes* to the input,

- the chance to get an unresolved outcome is *smaller*, but
- the *progress* is smaller, too!

We need a *compromise* between these two approaches!



Unresolved Test Outcomes (3)

Basic idea:

- 1. Start with few & large changes first
- 2. If all alternatives are unresolved, apply *more & smaller* changes.

This is achieved by splitting the initial Δ not into *two* subsets, but into an *increasing* number of subsets—as in *ddmin*!

Thus, we have to *merge* the binary search of the *ddbin* algorithm with the arbitrary number of subsets as in *ddmin*.

General Delta Debugging

Given: test, c_{\checkmark} , $c_{\bigstar} \cdot c_{\checkmark} \subseteq c_{\bigstar} \wedge test(c_{\checkmark}) = \checkmark \wedge test(c_{\bigstar}) = \bigstar$. Goal: $c'_{\checkmark}, c'_{\bigstar} = dd(c_{\checkmark}, c_{\bigstar})$ such that $c_{\checkmark} \subseteq c'_{\checkmark} \subseteq c'_{\bigstar} \subseteq c'_{\bigstar} \subseteq c'_{\bigstar}$ $test(c'_{\star}) = \checkmark, test(c'_{\star}) = \bigstar$ and each element of $\Delta = c'_{\mathbf{x}} \setminus c'_{\mathbf{y}}$ is relevant for the failure. Let $\Delta = c' \setminus c' = \Delta_1 \cup \cdots \cup \Delta_n$ in $dd(c_{\prime\prime}, c_{\prime\prime}) = dd'(c_{\prime\prime}, c_{\prime\prime}, 2)$ where $dd'(c'_{\mathbf{v}}, c'_{\mathbf{v}}, \mathbf{u}) = \begin{cases} dd'(c'_{\mathbf{v}}, c'_{\mathbf{v}} \cup \Delta_{i}, 2) & \text{if } \exists i \cdot test(c'_{\mathbf{v}} \cup \Delta_{i}) = \mathbf{x} \\ dd'(c'_{\mathbf{v}} \setminus \Delta_{i}, c'_{\mathbf{x}}, 2) & \text{if } \exists i \cdot test(c'_{\mathbf{x}} \setminus \Delta_{i}) = \mathbf{x} \\ dd'(c'_{\mathbf{v}} \cup \Delta_{i}, c'_{\mathbf{x}}, \max(n-1,2)) & \text{if } \exists i \cdot test(c'_{\mathbf{v}} \cup \Delta_{i}) = \mathbf{x} \\ dd'(c'_{\mathbf{v}}, c'_{\mathbf{x}} \setminus \Delta_{i}, \max(n-1,2)) & \text{if } \exists i \cdot test(c'_{\mathbf{x}} \setminus \Delta_{i}) = \mathbf{x} \\ dd'(c'_{\mathbf{v}}, c'_{\mathbf{x}}, \min(2n, |\Delta|)) & \text{if } 2n < |\Delta| \\ (c'_{\mathbf{v}}, c'_{\mathbf{x}}) & \text{otherwise} \end{cases}$ otherwise



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dd is the most general of all Delta Debugging algorithms:

- If *test* returns ✓ for c_✓ only, and ? in all other cases, then *dd* is equivalent to *ddmin*.
- If *test* never returns **?**, then *dd* is equivalent to *ddbin* (= binary search)

Consequence 1: You only need to know about *dd*. Period.

Consequence 2: *We must avoid unresolved test outcomes as good as we can* (e.g. by adding syntactic or semantic knowledge, as in simplification)





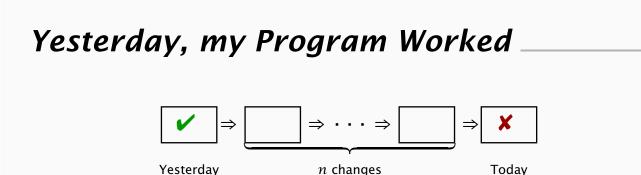
Application: Code Changes

Date: Fri, 31 Jul 1998 15:11:05 -0500 From: Brian Kahne <bkahne@ibmoto.com> To: DDD Bug Reports <bug-ddd@gnu.org> Subject: Problem with DDD and GDB 4.17

When using DDD with GDB 4.16, the run command correctly uses any prior command-line arguments, or the value of "set args". However, when I switched to GDB 4.17, this no longer worked: If I entered a run command in the console window, the prior command-line options would be lost. [...]







Assumption: The failure is caused by one of the changes between "yesterday" and "today".

Goal: Finding and examining this *failure-inducing change*.

Procedure: Delta Debugging



20/36

Trouble Ahead

In case of GDB, we have an enormous change:

\$ diff -r gdb-4.16 gdb-4.17 diff -r gdb-4.16/COPYING gdb-4.17/COPYING 5c5 < 675 Mass Ave, Cambridge, MA 02139, USA ---> 59 Temple Place, Suite 330, Boston, MA 02111-1307 USA 282c282 < Appendix: How to Apply These Terms to Your New Programs ---> How to Apply These Terms to Your New Programs :

and so on for a total of 178,200 lines.





Trouble Ahead (2)

Large changes are not the only source of trouble:

X Granularity. A single logical change can affect *thousands of lines of code*—but only a few lines may be responsible for the failure.

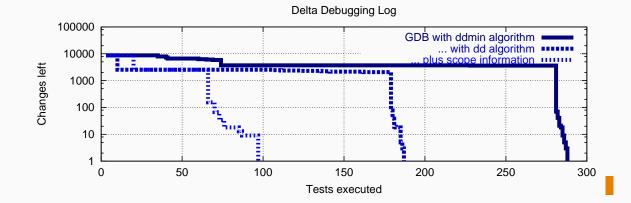
Example: integration of large third-party changes

- Interference. There can be *multiple* failure-inducing changes that cause the failure only when applied together.
 Example: integration of parallel development lines
- Inconsistency. The generated configuration may be inconsistent—we do not know whether the failure occurs.
 Example: change conflict, construction failure, crash

All these are handled by delta debugging.

Isolating the GDB Change

DIFF split into 8721 changes; 370s/test on 400 MHz PC



The failure-inducing code change is:

diff -r gdb-4.16/gdb/infcmd.c gdb-4.17/gdb/infcmd.c
1239c1278
< "Set arguments to give program being debugged when it is started.\n\
--> "Set argument list to give program being debugged when it is started.\n\

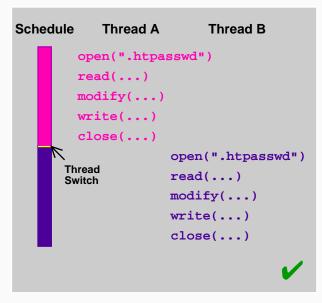


23/36



Application: Thread Schedules

The behavior of a multi-threaded program can depend on the *thread schedule:*



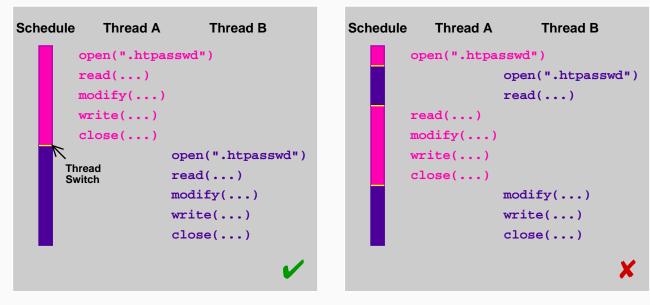




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Application: Thread Schedules

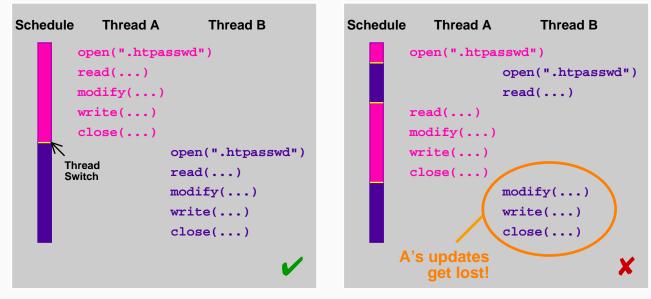
The behavior of a multi-threaded program can depend on the *thread schedule:*





Application: Thread Schedules

The behavior of a multi-threaded program can depend on the *thread schedule:*



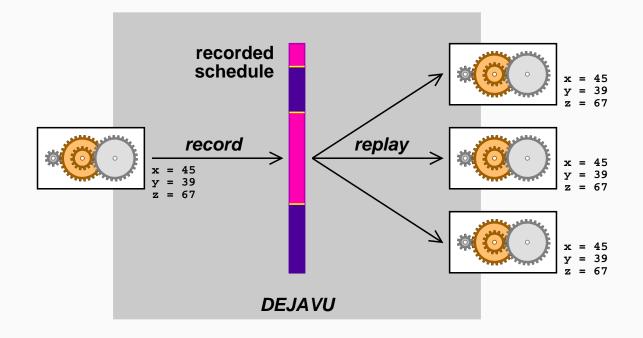
Thread switches and schedules are *nondeterministic:* Bugs are *hard to reproduce* and *hard to isolate!*





Recording and Replaying Runs

DEJAVU captures and replays program runs deterministically:

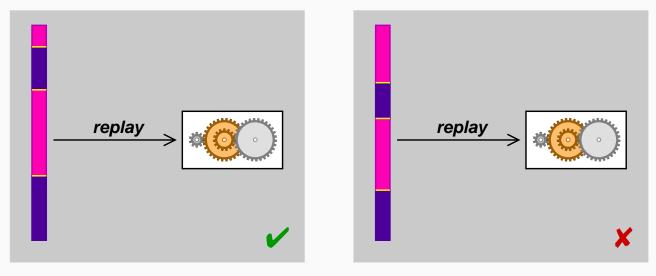


Allows simple *reproduction* of schedules and induced failures

Differences between Schedules

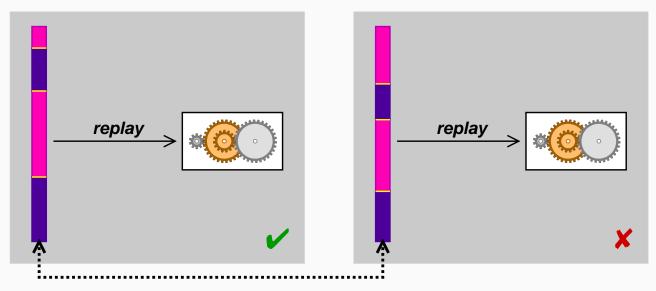
Using DEJAVU, we can consider the schedule as an *input* which determines whether the program passes or fails.

26/36



Differences between Schedules

Using DEJAVU, we can consider the schedule as an *input* which determines whether the program passes or fails.

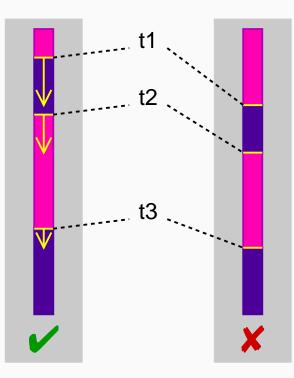


The *difference* between schedules is relevant for the failure: A *small* difference can pinpoint the failure cause





Finding Differences



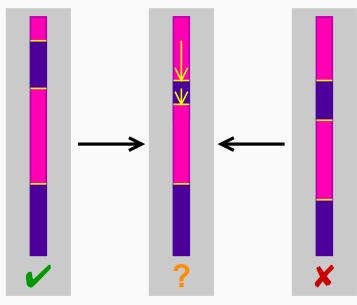
- We start with runs 🗸 and 🗙
- We determine the differences Δ_i between thread switches t_i :
 - t_1 occurs in \checkmark at "time" 254
 - t_1 occurs in X at "time" 278
 - The difference $\Delta_1 = |278 - 254|$ induces a *statement interval:* the code executed between "time" 254 and 278
 - Same applies to t_2 , t_3 , etc.

Our goal: *Narrow down* the difference such that only a small *relevant difference* remains, pinpointing the root cause

27/36

Isolating Relevant Differences

We use *Delta Debugging* to isolate the relevant differences Delta Debugging applies *subsets* of differences to **/**:

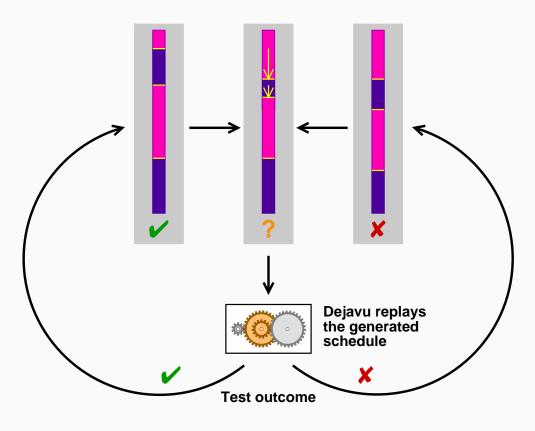


- The *entire* difference Δ_1 is applied
- Half of the difference Δ_2 is applied
- Δ_3 is not applied at all

DEJAVU executes the debuggee under this *generated* schedule; an automated test checks if the failure occurs

The Isolation Process

Delta Debugging systematically narrows down the difference



29/36

A Real Program

We examine Test #205 of the SPEC JVM98 Java test suite: a raytracer program depicting a dinosaur

Program is single-threaded—the multi-threaded code is commented out

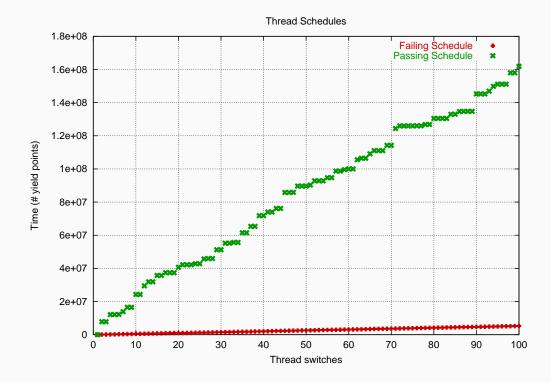
To test our approach,

- we make the raytracer program *multi-threaded* again
- we introduce a simple *race condition*
- we implement an *automated test* that would check whether the failure occurs or not
- we generate *random schedules* until we obtain both a passing schedule (*) and a failing schedule (*)



Passing and Failing Schedule

We obtain two schedules with 3,842,577,240 differences, each moving a thread switch by ± 1 "time" unit

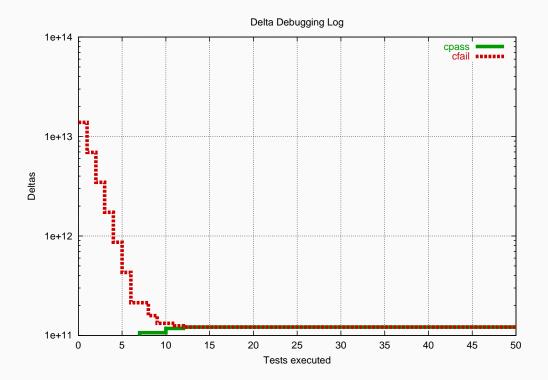


31/36



Narrowing Down the Failure Cause

Delta Debugging isolates one single difference after 50 tests:





The Root Cause of the Failure

```
25 public class Scene { ...
       private static int ScenesLoaded = 0;
44
       (more methods...)
45
       private
81
       int LoadScene(String filename) {
82
            int 01dScenesLoaded = ScenesLoaded;
84
           (more initializations...)
85
           infile = new DataInputStream(...);
91
           (more code...)
92
           ScenesLoaded = 01dScenesLoaded + 1;
130
           System.out.println("" +
131
                 ScenesLoaded + " scenes loaded.");
132
134
135
733 }
```



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Consequence

Still, processor speed doubles almost every 18 months (Moore's Law).

Consequence: We can now afford approaches that were way too expensive only a few years ago.

Currently, the computer spends 99.9% of its time just waiting for the programmer to move the mouse.

We can exploit this to have

- Expensive program analysis
- Automated testing
- Automated debugging





Concepts

- In contrast to simplification, *isolation* finds only *one* relevant part of the test case; removing *this particular part* makes the failure go away
- Isolation is *much more efficient* than simplification.





Concepts (2)

- The general Delta Debugging algorithm *dd* extends *ddmin* to isolate failure-inducing differences.
- *dd* becomes an efficient binary search as soon as there are no unresolved test outcomes
- Delta Debugging can be applied to *arbitrary circumstances* of the program run:
 - Program input
 - Program code
 - Program environment (i.e., the thread schedule)

as long as there is an automated test and a passing configuration to compare with.